## CS5733 Program Synthesis

**#17.** Hoare Logic and Synthesis

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With slides from Nadia Polikarpova and Yu-Fang Chen

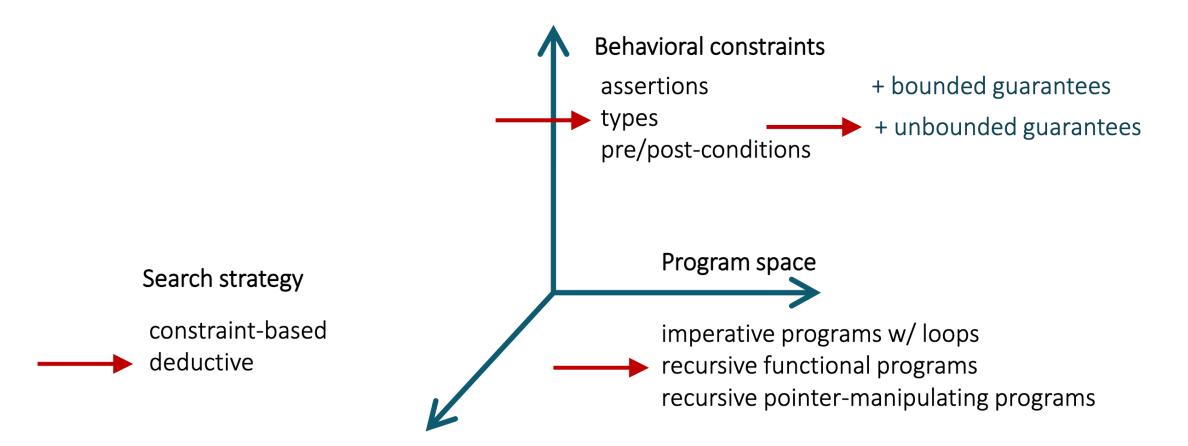
### **Module II**

Behavioral constraints + bounded guarantees assertions types + unbounded guarantees pre/post-conditions Program space imperative programs w/loops recursive functional programs recursive pointer-manipulating programs

Search strategy constraint-based

deductive

### Last week



### This week

Behavioral constraints + bounded guarantees assertions types + unbounded guarantees pre/post-conditions Program space imperative programs w/ loops recursive functional programs recursive pointer-manipulating programs

Search strategy

constraint-based deductive

### Constraint-based synthesis

Behavioral constraints = assertions, reference implementation, pre/post

encoding

Structural constraints

 $\exists c . \forall x . Q(c,x)$ 

### Why is this hard?

```
Euclid (int a, int b) returns (int x)
                                                              infinitely many inputs
  requires a > 0 \land b > 0
  ensures x = \gcd(a, b)
  int x , y := a, b;
                                                               infinitely many paths!
  while (x != y) {
    if (x > y) x := ??*x + ??*y + ??;
else y := ??*x + ??*y + ??;
}}
```

### Loop unrolling is unsound and incomplete

```
Euclid (int a, int b) returns (int x)
  requires a > 0 \land b > 0
  ensures x = \gcd(a, b)
                                                      if (x != y) {
  int x , y := a, b;
                                                        if (x > y)
 while (x != y) {
                                                          x := ??*x + ??*y + ??;
                                           Unroll with
    if (x > y) x := ??*x + ??*y + ??;
                                                        else
                                           depth = 1
                                                          y := ??*x + ??*y + ??;
    else y := ??*x + ??*y + ??;
                                                        assert !(x != y);
}}
```

### Loop unrolling is unsound and incomplete

```
Euclid (int a, int b) returns (int x)
                                                                      Unsatisfiable sketch
  requires a > 0 \land b > 0
  ensures x = \gcd(a, b)
                                                       if (x != y) {
  int x , y := a, b;
                                                         if (x > y)
 while (x != y) {
                                                           x := ??*x + ??*y + ??;
                                           Unroll with
    if (x > y) x := ??*x + ??*y + ??;
                                                         else
                                           depth = 1
                                                           y := ??*x + ??*y + ??;
    else y := ??*x + ??*y + ??;
                                                         assert !(x != y);
}}
```

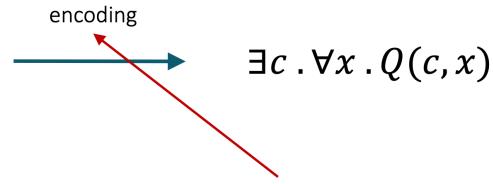
### Loop unrolling is unsound and incomplete

```
What if we restrict inputs to
                                                    [1, 2]?
Euclid (int a, int b) returns (int x)
                                                                       Unsound solution!
  requires a > 0 \land b > 0
  ensures x = \gcd(a, b)
                                                        if (x != y) {
  int x , y := a, b;
                                                          if (x > y)
 while (x != y) {
                                                            x := 0 *x + 0 *y + 1;
                                            Unroll with
    if (x > y) x := ??*x + ??*y + ??;
                                                          else
                                            depth = 1
                                                            y := 0 *x + 0 *y + 1;
    else y := ??*x + ??*y + ??;
                                                          assert !(x != y);
}}
```

### Constraint-based synthesis

Behavioral constraints = assertions, reference implementation, pre/post

Structural constraints



If we want to synthesize programs that are correct on all inputs, we need a better way to deal with loops!

### Solution

Hoare logic = a program logic for simple imperative programs

• in particular: loop invariants

### The Imp language

### Hoare triples

Properties of programs are specified as judgments

$$\{P\} c \{Q\}$$

where c is a command and  $P, Q: \sigma \rightarrow Bool$  are predicates

• e.g. if  $\sigma = [x \mapsto 2]$  and  $P \equiv x > 0$  then  $P \sigma = T$ 

#### **Terminology**

- Judgments of this kind are called (Hoare) triples
- P is called precondition
- *Q* is called postcondition

### Meaning of Triples

#### The meaning of $\{P\}$ c $\{Q\}$ is:

- if P holds in the initial state  $\sigma$ , and
- if the execution of c from  $\sigma$  terminates in a state  $\sigma'$
- then Q holds in  $\sigma'$

#### This interpretation is called *partial correctness*

termination is not essential

#### Another possible interpretation: total correctness

- if P holds in the initial state  $\sigma$
- then the execution of c from  $\sigma$  terminates in a state (call it  $\sigma'$ )
- and Q holds in  $\sigma'$

### Example: swap

```
{T}

x := x + y; y := x - y; x := x - y

\{x = y \land y = x\}
```

We have to express that y in the final state is equal to x in the initial state!

### Logical Variables

```
\{x = N \land y = M\}

x := x + y; y := x - y; x := x - y

\{x = M \land y = N\}
```

#### Assertions can contain *logical variables*

- may occur only in pre- and postconditions, not in programs
- the state maps logical variables to their values, just like normal variables

### Inference system

- Similar to the Logical System in PL and FOL.
- Called as the Hoare Logic

We formalize the semantics of a language by describing which judgments are valid about a program

#### An inference system

• a set of *axioms* and *inference rules* that describe how to derive a valid judgment

We combine axioms and inference rules to build *inference trees* (derivations)

### Semantics of skip

**skip** does not modify the state

```
{ P } skip { P }
```

### Semantics of assignment

```
\{x > 0\} \ x := x + 1 \{???\}
```

$$\{???\} x := x + 1 \{x > 1\}$$

### Semantics of Assignment

We begin with Foyld's version of the assignment axiom {P} X := E {?}

The term **E** might contain **X**, e.g.  $\mathbf{E} \equiv \mathbf{X+1}$ 

An example: X := X + 1

The value of X **after** executing the statement

The value of X **before** executing the statement

We need to differentiate these two values!

### Floyd's version

We begin with Foyld's version of the assignment axiom {P} X := E {?}

$$\exists V.(X=E[V/X] \land P[V/X])$$

Intuition: we use new variable V to denote the **old value of X** 

## Notations E[V/X] replacing all free occurrences of X in P with V

### Flyod's version

#### **Foyld's Assignment Axiom**

$$\{P\} X := E \{ \exists V. X = E[V/X] \land P[V/X] \}$$

#### **Example**

$$\{Y + X = 42\} X := X + 5 \{\exists V. X = V + 5 \land Y + V = 42\}$$

#### **Example**

$${Y = 5} X := X/Y + X {?}$$

We do not want to have quantifiers in the reasoning path!

### Hoare's backward semantics of assignment

x := e assigns the value of e to variable x

$$\{P[x \mapsto e]\}\ x \coloneqq e \{P\}$$

- Let  $\sigma$  be the initial state
- Precondition:  $(P[x \mapsto e])\sigma$ , i.e.,  $P(\sigma[x \mapsto \mathcal{A}[\![e]\!]\sigma])$
- Final state:  $\sigma' = \sigma[x \mapsto \mathcal{A}[e]\sigma]$
- Consequently, P holds in the final state

### Hoare's backward semantics

#### Backward reasoning

Hoare's Assignment Axiom

{Q[E/X]} X:=E {Q}

Read as If Q holds in the post-condition then ...

Let s be the state before X := E and s' the state after. So,  $s' = s[X \rightarrow E]$  (assuming E has no side-effect).

Q[E/X] holds in s if and only if Q holds in s', because

- (1) Every variable, except X, has the same value in s and s', and
- (2) Q[E/X] has every X in Q replaced by E,
- (3) Q has every X evaluated to E in s (s' = s[X  $\rightarrow$  E]).

### Semantics of composition

Sequential composition **c1**; **c2** executes **c1** to produce an intermediate state and from there executes **c2** 

$$\frac{\{P\}\ c_1\ \{R\}\ c_2\ \{Q\}}{\{P\}\ c_1; c_2\ \{Q\}}$$

### Example: swap

$$\{P[x \mapsto e]\}\ x \coloneqq e \{P\}$$

leaves = axioms

#### inference tree

$$\{x = N \land y = M\}$$
  $x := x + y \quad \{y = M \land x - y = N\}$ 

edges = rules

$$\{y = M \land x - y = N\} \quad y := x - y \quad \{x - y = M \land y = N\}$$

 $\{x = N \land y = M\} \ x := x + y; \ y := x - y \ \{x - y = M \land y = N\}$ 

$$\{x - y = M \land y = N\} \quad \mathbf{x} := \mathbf{x} - \mathbf{y} \quad \{x = M \land y = N\}$$
 assign

\_\_\_\_\_ comp

assign

$$\{x = N \land y = M\} \ x := x + y; \ y := x - y; \ x := x - y \ \{x = M \land y = N\}$$

root = triple to prove

#### **Proof outline**

$$\{P[x \mapsto e]\}\ x \coloneqq e\ \{P\}$$

An alternative (more compact) representation of inference trees

$$\{x = N \land y = M\}$$

$$\Rightarrow$$

$$\{(x + y) - ((x + y) - y) = M \land (x + y) - y = N\}$$

$$x = x + y;$$

$$\{x - (x - y) = M \land x - y = N\}$$

$$y = x - y;$$

$$\{x - y = M \land y = N\}$$

$$x = x - y$$

$$\{x = M \land y = N\}$$

### Try out example

#### **Example**

P: {true} X:=2 ; Y:=X {X > 0∧ Y=2}

- (1)  $2>0 \land 2 = 2 \Leftrightarrow \text{true (Integer arithmetic)}$
- (2)  $\{2 > 0 \land 2 = 2\}$  X:=2  $\{X > 0 \land X = 2\}$  (assignment axiom)
- (3)  $\{X > 0 \land X = 2\} Y := X \{X > 0 \land Y = 2\}$  (assignment axiom)
- (4)  $\{\text{true}\}\ X:=2\ \{X>0 \land X=2\}\ (\text{by (1)}, \text{ we can replace } 2>0 \land 2=2 \text{ in (3) with true )}$
- (5)  $\{\text{true}\}\ X:=2\ ;\ Y:=X\ \{X>0\land\ Y=2\}\ (\text{by (3), (4), and composition rule})$

### Rule of consequence

$$\frac{\{P'\}\ c\ \{Q'\}}{\{P\}\ c\ \{Q\}} \quad \text{if} \quad P \Rightarrow P' \land Q' \Rightarrow Q$$

Corresponds to adding  $\Rightarrow$  steps in a proof outline Here  $P \Rightarrow P'$  should be read as

• "We can prove for all states  $\sigma$ , that P  $\sigma$  implies P'  $\sigma$ "

### Consequence rule

## Consequence Rule $\frac{P \Rightarrow P' \{P'\} \ S \{Q'\} \ Q' \Rightarrow Q}{\{P\} \ S \{Q\}}$

- We can strengthen the precondition, i.e. assume more than we need
- We can weaken the postcondition, i.e. conclude less than we are allowed to

### Consequence rule

#### **Consequence Rule**

$$\frac{P \Rightarrow P' \{P'\} S \{Q'\} Q' \Rightarrow Q}{\{P\} S \{Q\}}$$

#### **Example**

$$P_1$$
: {true  $\land$  X < 10} X:=10 {X=10  $\lor$  X=0}

- (1) {true} X:=10 {X=10 ∨ X=0} (by Assignment Rule)
- (2) true ∧X<10 ⇒ true (by underlying logic)
- (3)  $X = 10 \lor X = 0 \Rightarrow X = 10 \lor X = 0$  (by underlying logic)
- (4)  $\{\text{true} \land X < 10\} \ X = 10 \ \{X = 10 \lor X = 0\} \ (\text{by consequence rule, (2), and (3)})$

### Consequence rule

#### **Consequence Rule**

$$P \Rightarrow P' \{P'\} S \{Q'\} Q' \Rightarrow Q$$
$$\{P\} S \{Q\}$$

#### **Example**

$$P_2$$
: {true  $\land X \ge 10$ } X:=0 {X=10  $\lor X=0$ }

Try it yourself!

### Semantics of conditionals

$$\frac{\{P \land e\} c_1 \{Q\}}{\{P\} \text{ if } e \text{ then } c_1 \text{ else } c_2 \{Q\}}$$

### Example: absolute value

```
{T}
       if x < 0 then
        \Rightarrow \begin{cases} \top \land x < 0 \\ -x \ge 0 \end{cases}
            x := -x
            \{x \ge 0\}
       else
        \Rightarrow^{\{\neg(x<0)\}}
            \{x \ge 0\}
             skip
            \{x \ge 0\}
\{x \ge 0\}
```

$$\frac{\{P \land e\} \ c_1 \ \{Q\} \qquad \{P \land \neg e\} \ c_2 \ \{Q\}}{\{P\} \ \text{if} \ e \ \text{then} \ c_1 \ \text{else} \ c_2 \ \{Q\}}$$

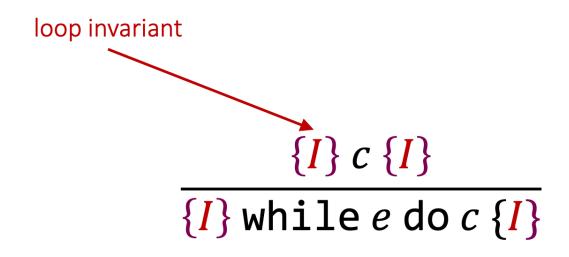
# Hoare Logic Continued...

### Semantics of loops

$$\frac{\{?\} c \{?\}}{\{P\} \text{ while } e \text{ do } c \{Q\}}$$

Challenge: c needs to execute multiple times with the same pre/post

### Semantics of loops



**Challenge:** c needs to execute multiple times with the same pre/post **Solution:** make its pre and post *the same*!

called a loop invariant

### Semantics of loops

$$\frac{\{I \land e\} c \{I\}}{\{I\} \text{ while } e \text{ do } c \{\neg e \land I\}}$$

Challenge: c needs to execute multiple times with the same pre/post Solution: make its pre and post the same!

- called a *loop invariant*
- + strengthen the semantics with the info about the loop condition

### **Example: GCD**

```
\{x = N \land y = M \land N > 0 \land M > 0\}
  \Rightarrow
{I}
    while x != y do
       {I \land x \neq y}
          if x > y then
            x := x - y
          else
             y := y - x
       {I}
{I \land x = y}
  \Rightarrow
{x = \gcd(N, M)}
```

Guessing the loop invariant:

 $I \equiv \gcd(x, y) = \gcd(N, M)$ 

### **Example: GCD**

```
\{x = N \land y = M \land N > 0 \land M > 0\}
\{\gcd(x,y)=\gcd(N,M)\land x,y>0\}
   while x != y do
      \{\gcd(x,y)=\gcd(N,M)\land x,y>0\land x\neq y\}
        if x > y then
          \{\gcd(x,y)=\gcd(N,M)\land x\neq y\land x>y\}
          \{\gcd(x-y,y)=\gcd(N,M)\land x-y,y>0\}
             x := x - y
           \{\gcd(x,y)=\gcd(N,M)\land x,y>0\}
        else
             y := y - x
      \{\gcd(x,y)=\gcd(N,M)\land x,y>0\}
\{\gcd(x,y)=\gcd(N,M)\land x,y>0\land x=y\}
 \Rightarrow
\{x = \gcd(N, M)\}
```

### **Termination**

### **Example: GCD**

### **Example: GCD**

```
\{x = N \land y = M \land N > 0 \land M > 0\}
  \Rightarrow
\{\gcd(x,y)=\gcd(N,M)\land x,y>0\}
    while x != y do
      \{\gcd(x,y)=\gcd(N,M)\land x,y>0\land x+y=R\land x\neq y\}
         if x > y then
              x := x - y
         else
              y := y - x
      \{\gcd(x,y)=\gcd(N,M)\land x,y>0\land x+y< R\land x+y\geq 0\}
\{\gcd(x,y)=\gcd(N,M)\land x,y>0\land x=y\}
  \Rightarrow
\{x = \gcd(N, M)\}
```

### **Program Verification**

```
method Euclid (a: int, b: int) returns (gcd: int)
    requires a > 0 && b > 0
    ensures x == gcd(a,b)
{
    var x, y := a, b;
    while (x != y)
        invariant y > 0 && x > 0 && gcd(x,y) == gcd(a,b)
        decreases x + y
    {
        if (x > y) {
            x := x - y;
        } else {
            y := y - x;
        }
    }
}

    Dafny

    correct!
    can't proof
    correctness
    y := y - x;
}
```

### Program synthesis

```
method Euclid (a: int, b: int) returns (gcd: int)
  requires a > 0 && b > 0
  ensures x == gcd(a,b)
{
  var x, y := ?;
  ?;
  while (?)
    invariant ?
    decreases ?
  {
    ?;
  }
  ?;
}
```

found a correct program!

```
var x, y := a, b;
while (x != y)
  invariant y > 0 && x > 0 && gcd(x,y) == gcd(a,b)
  decreases x + y
{
  if (x > y) {
    x := x - y;
  } else {
    y := y - x;
  }
}
```



can't find a (program, invariant) pair that I can prove correct

### Verification $\rightarrow$ synthesis

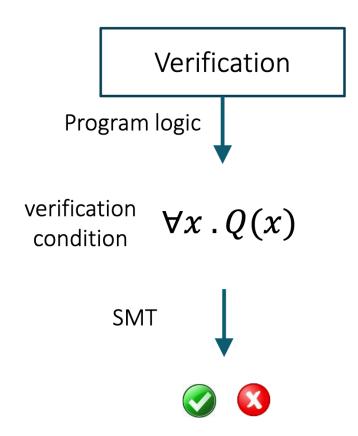
Srivastava, Gulwani, Foster: From program verification to program synthesis. POPL'10

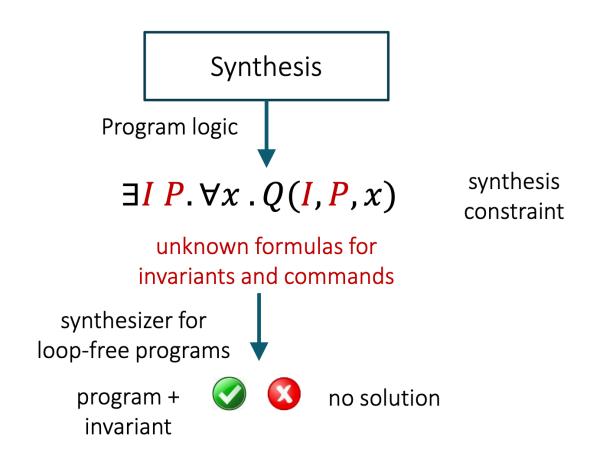
- idea: make constraint-based synthesis unbounded by synthesizing loop invariants alongside programs
- synthesized some looping programs with integers, including Bresenheim algorithm
- won "Most Influential Paper" at POPL'20!

Qiu, Solar-Lezama: Natural Synthesis of Provably-Correct Data-Structure Manipulations. OOPSLA'17

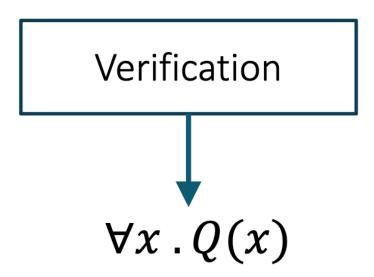
same approach for pointer-manipulating programs

### Verification → synthesis





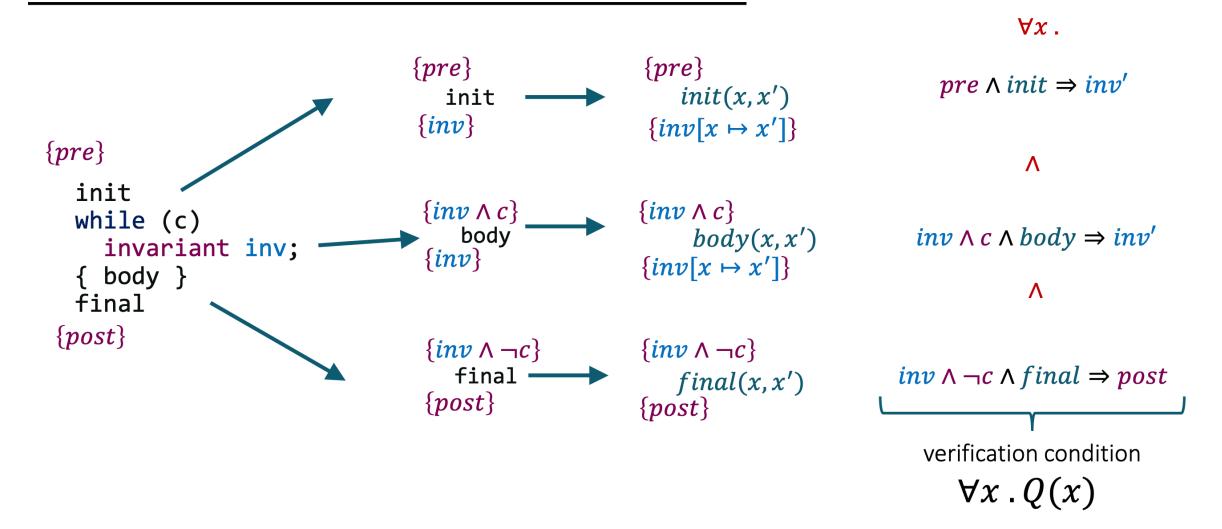
### How verification works



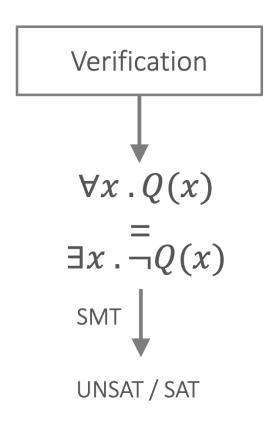
### Step 1: eliminate loops

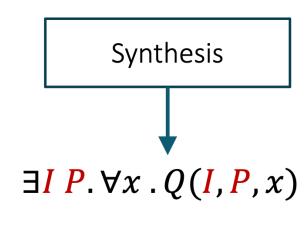
```
{pre}
                                                   init;
                                                 {inv }
{pre}
                                                            \{inv \land cond \}
   init;
   while (c)
                                                               body;
      invariant inv
                                                            {inv}
    { body; }
   final;
{post}
                                                 \{inv \land \neg(cond)\}
                                                   final;
                                                  {post}
```

### Step 2: generate VCs

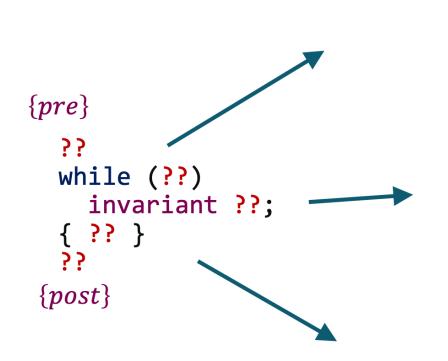


### From verification to synthesis





### Program synthesis



```
{pre}
    S_i(x,x')
\{I[x \mapsto x']\}
 \{I \wedge G\}
     S_b(x,x')
 \{I[x \mapsto x']\}
 \{I \land \neg G_0\}
       S_f(x,x')
  {post}
```

```
\exists S \ G \ I. \forall x.
         pre \land S_i \Rightarrow I'
                       Λ
         I \wedge G \wedge S_b \Rightarrow I'
                       Λ
       I \land \neg G \land S_f \Rightarrow post
     synthesis constraint
\exists I P. \forall x . Q(I, P, x)
```

### Synthesis constraints

$$pre \land S_i \Rightarrow I'$$

$$I \land G \land S_b \Rightarrow I'$$

$$I \land \neg G \land S_f \Rightarrow post$$

Domain for I, G: formulas over program variables

Domain for 
$$S = \{x' = e_x \land y' = e_y \land \cdots \mid e_x, e_y, \ldots \in Expr\}$$

• conjunction of equalities, one per variables

### Solving synthesis constraints

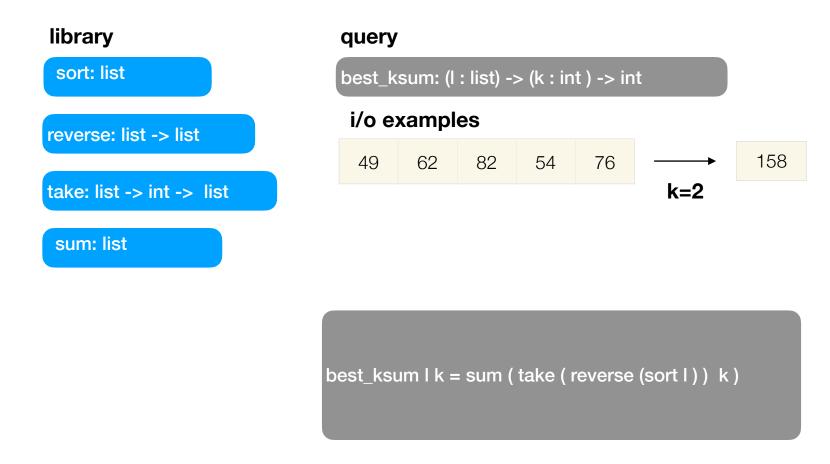
$$pre \land S_i \Rightarrow I'$$
 $I \land G \land S_b \Rightarrow I'$ 
 $I \land \neg G \land S_f \Rightarrow post$ 

### Can be solved this with...

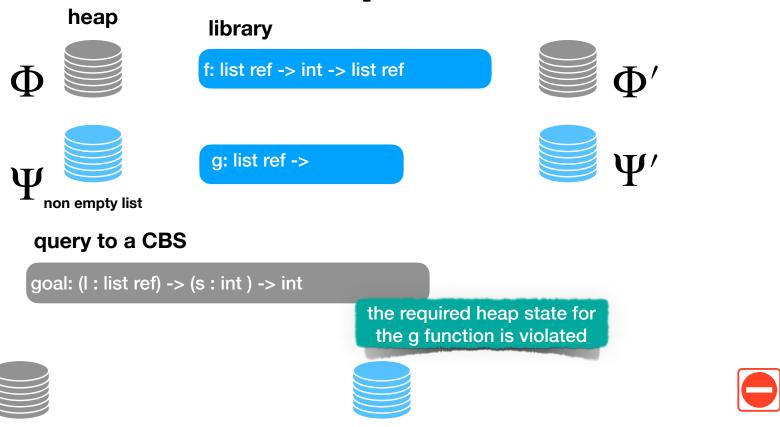
- SyGuS solvers
- Sketch
  - Look we made an unbounded synthesizer out of Sketch!
- VS3 uses Lattice search
  - More efficient for predicates

## Component-based synthesis using Hoare Logic

# Component-based synthesis (CBS)



# CBS: with effectful components



A sound synthesizer must take changing heap state and library protocol into account

a blowup in the space of programs

### A query over a mutable Table

#### Library

```
type pair = Pair of float * int
type table = [string] ref
add tbl: adds a string in the table if not already
present.
mem_tbl: checks if a string is in the table
fresh str: returns a fresh string not in the table.
size tbl: gives the size of the tbl
average_len_tbl : gives a float value equall to
the average length of the strings in the table
```

Maintains a Uniqueness Invariant

```
Query
add_and_incr: (tbl: table * s: string)→
                returns a pair type
pair
                no constraints on the initial
(*requires*)
                           table
{true}
                     updates the table to include s
 (*ensures*)
                        and increment size by 1
 { mem (Tbl', s) ^
size (Tbl') = size (Tbl) + 1;
                         Tbl, Tbl': [string]
add and incr (tbl : table * s :string) =
??
```

### Effect agnostic CBS on query

violates uniqueness property of add\_tbl

What if s is already in tbl?

```
add_and_incr : (tbl : table * s :
string) →
  (*requires*)
{true}
v : pair
  (*ensures*)
{ mem (Tbl', s) ∧
  size (Tbl') = size (Tbl) + 1};
```

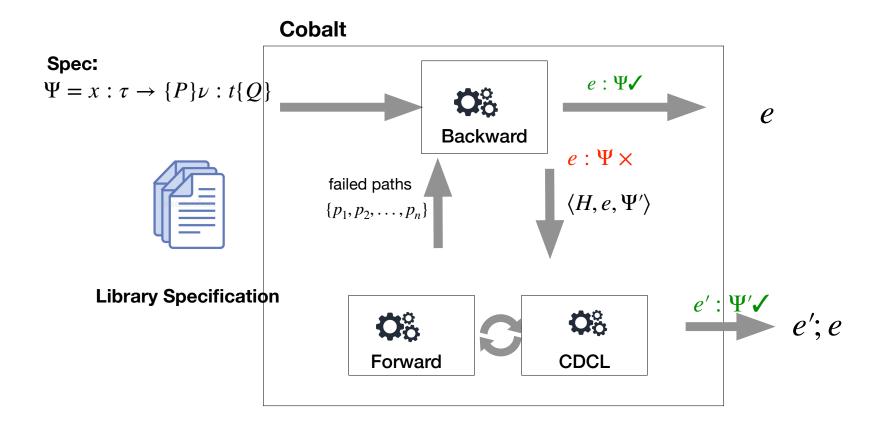


creates a fresh string if s already in tbl

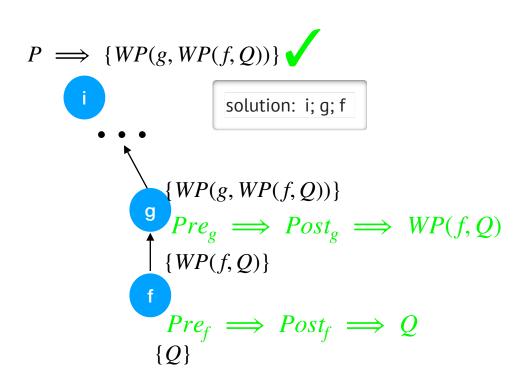
```
add_and_incr (tbl : table * s : string) =
   _ ← add_tbl (tbl, s);
   x1 ← average_len_tbl (tbl);
   y1 ← size_tbl (tbl);
   return Pair (x1, y1)
```

**Cobalt solution** 

### Overview: Cobalt



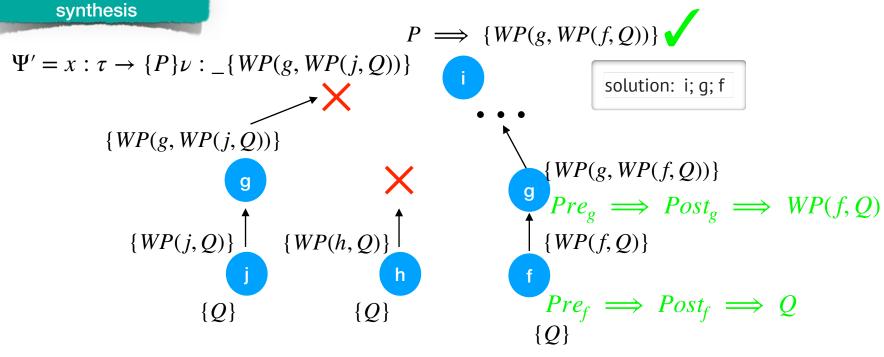
## Backward synthesis



Spec 
$$\Psi = x : \tau \to \{P\}\nu : t\{Q\}$$

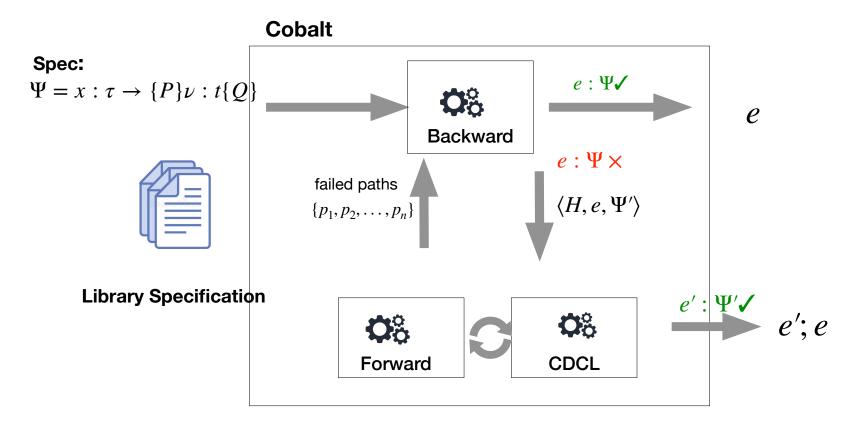
### **Backward synthesis**

Handover to forward synthesis



Spec 
$$\Psi = x : \tau \to \{P\}\nu : t\{Q\}$$

## Forward synthesis



# finite-depth Forward synthesis

Spec 
$$\Psi = x : \tau \rightarrow \{P\}\nu : t\{Q\}$$
 $\{P\} \implies Pre_f$ 

$$\{SP(P,f)\}\nu : t\{Q\}$$

$$\{SP(P,f)\} \implies Pre_g$$

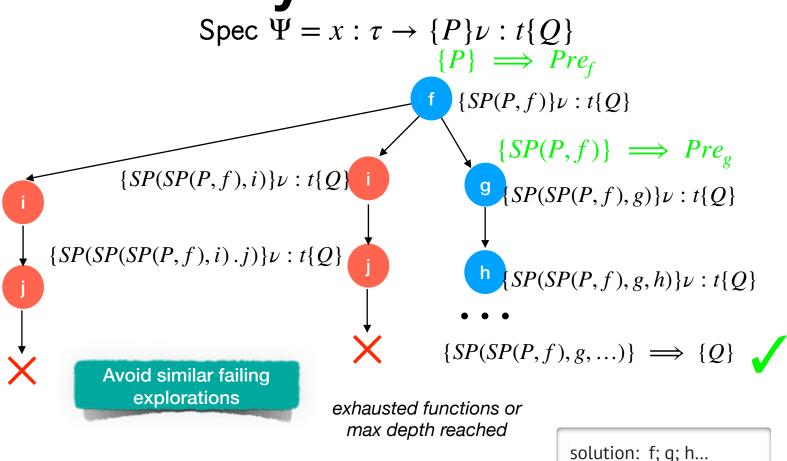
$$\{SP(SP(P,f),g)\}\nu : t\{Q\}$$

$$\{SP(SP(P,f),g,h)\}\nu : t\{Q\}$$

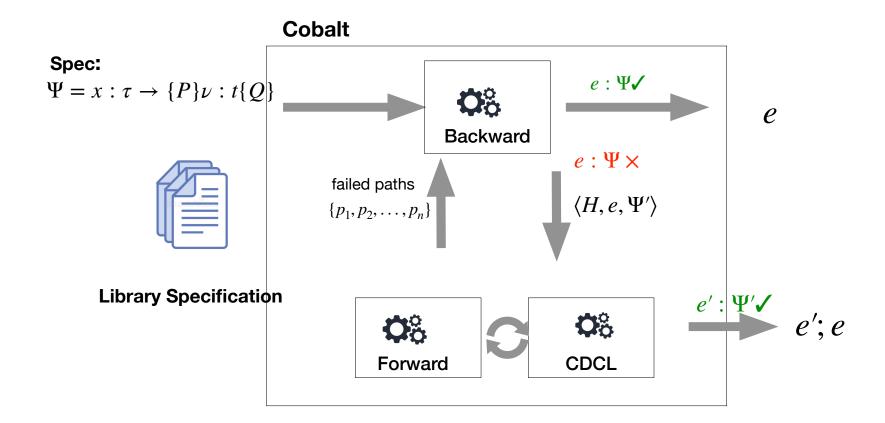
$$\{SP(SP(P,f),g,...)\} \implies \{Q\}$$

$$\{SP(SP(P,f),g,...)\} \implies \{Q\}$$

# finite-depth forward synthesis



### CDCL search



### Revisiting the query

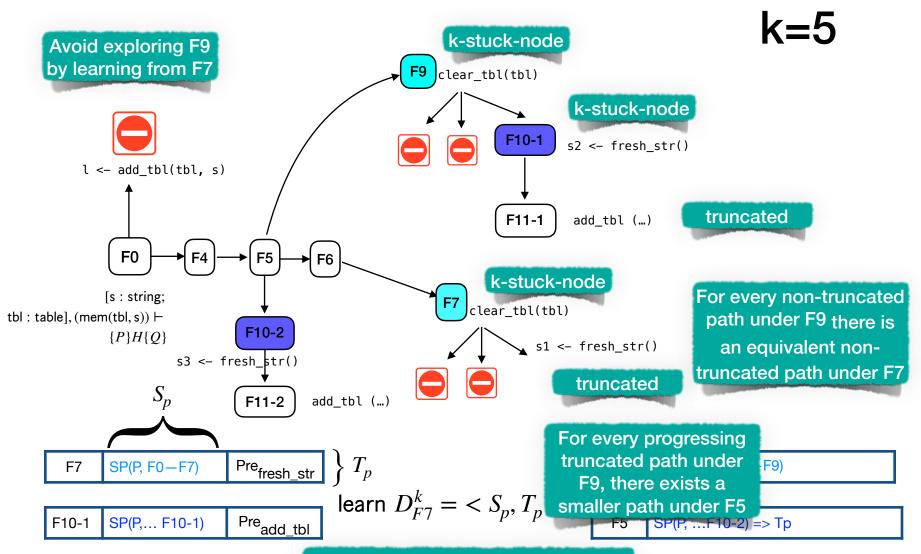
### Query

```
add_and_incr : (tbl : table * s :
string) →
  (*requires*)
{true}
v : pair
  (*ensures*)
{ mem (Tbl', s) ∧
size (Tbl') = size (Tbl) + 1};
```



subquery for when s is in the table

### finite-depth CDCL search



F9 and F7 are k-equivalent modulo stuckness

### Synthesis guarantees

The synthesis algorithm is sound and complete.

```
Theorem (Soundness): For a given (\Gamma, \Sigma, \Psi) Cobalt synthesizes a term e then \Gamma \vdash e : \Psi Type Environment, Library and Specification
```

**Theorem (Completeness):** For all k, for a given  $(\Gamma, \Sigma, \Psi)$ Cobalt fails to find a solution then there exists no e of size (e) <= k, such that  $\Gamma \vdash e : \Psi$